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Directed Reading Program

A Geometric Approach of Differential Forms

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# A problem with parametric integration

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**Proof.**

if  $\phi_1(x) = (x, \sqrt{1-x^2})$  and  $\phi_2(\theta) = (\cos(\theta), \sin(\theta))$

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Our problem stems from the fact that the points  $\phi_1(a_i)$  are not evenly spaced along the curve

# A calculated transformation

Using Riemann sums we can find an appropriate integral

$$\sum_{i=1}^n F(a_i)\Delta a = \sum_{i=1}^n f(\phi_1(a_i))L_i \text{ as } n \text{ goes to infinity}$$

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$\lim_{\Delta a \rightarrow 0} F(a_i) = \lim_{\Delta a \rightarrow 0} \frac{f(\phi_1(a_i)) L_i}{\Delta a}$  when boiled down has

$$F(a) = f(\phi_1(a_i)) \left| \frac{d\phi_1}{da} \right| da$$

for lines in  $\mathbb{R}^2$  and similarly for surfaces in  $\mathbb{R}^3$

$$F(a) = f(\phi(a, b)) \text{Area} \left( \frac{d\phi}{da}, \frac{d\phi}{db} \right) da db$$

# Forms

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The vectors fed exist on on the tangent space to a point denoted by  $T_p\mathbb{R}^2$  for a line and  $T_p\mathbb{R}^3$  for a surface

# Multiplying 1-forms

The multiplication of two one forms, say  $\omega(V_1)$  and  $v(V_2)$ , is considered a 2-form and denoted by  $\omega \wedge v(V_1, V_2)$  and is evaluated in the following way:

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## Definition

for  $\omega = ax + by + cz$ ,  $\langle \omega \rangle = \langle a, b, c \rangle$

It is possible to show through the linearity of forms two unique geometric and algebraic definitions

$$\omega \wedge v = |\langle \omega \rangle| |\langle v \rangle| \bar{\omega} \wedge \bar{v}$$

Evaluating  $\omega \wedge v$  on the pair of vectors  $(V_1, V_2)$  gives the area of the parallelogram spanned by  $V_1$  and  $V_2$  projected onto the plane containing the vectors  $\langle \omega \rangle$  and  $\langle v \rangle$ , and multiplied by the area of the parallelogram spanned by  $\langle \omega \rangle$  and  $\langle v \rangle$

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$$\omega \wedge v = c_1 dx \wedge dy + c_2 dx \wedge dz + c_3 dy \wedge dz$$

Every 2-form projects the parallelogram spanned by  $V_1$  and  $V_2$  onto each of the (2-dimensional) coordinate planes, computes the resulting (signed) areas, multiplies each by some constant, and adds the results

# Differential Forms

Forms that are differentiable on a given interval can be used more easily for our integral previously on the part which involved  $\text{Area}\left(\frac{d\phi}{da}, \frac{d\phi}{db}\right)$



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## Example

for the differential 2 form acting on two vector fields

$V_1 = \langle 2y, 0, -x \rangle$  and  $V_2 = \langle z, 1, xy \rangle$  with

$\omega = x^2 y dx \wedge dy - xz dy \wedge dz$

$$\omega(V_1, V_2) = x^2 y \begin{vmatrix} 2y & z \\ 0 & 1 \end{vmatrix} - xz \begin{vmatrix} 0 & 1 \\ -x & xy \end{vmatrix} = 2x^2 y^2 - x^2 z$$

# Integrating Forms

Through a similar proof as with the integral of a function we associate the integral of a 2-form in  $\mathbb{R}^3$  through equivalent Riemann sums

$$\sum_i \sum_j f(x_i, y_j) dx \wedge dy(V_{i,j}^1, V_{i,j}^2) = \sum_i \sum_j \omega_{\phi(x_i, y_j)}(\mathbb{V}_{i,j}^1, \mathbb{V}_{i,j}^2)$$

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Through extensive calculations becomes:

$$\int_M \omega = \int_R \omega_{\phi(x,y)} \left( \frac{\partial \phi}{\partial x}, \frac{\partial \phi}{\partial y} \right) dx \wedge dy$$

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The orientation of the parametrization is crucial and can switch based on the choice of  $V_{i,j}^1$  and  $-V_{i,j}^1$

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## Example

for  $\omega = ydx - x^2dy$  with  $V = \langle 1, 2 \rangle$  and  $W = \langle 2, 3 \rangle$

$$d\omega = \langle -4x, 1 \rangle \cdot \langle 2, 3 \rangle = -8x + 3$$

# An Approach to Stokes Theorem

an  $n$ -cell is defined as the image of a differentiable map and denoted by  $\sigma$  where as a chain is a formal linear combination of  $n$ -cells where

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the boundary of a  $n$ -cell is denoted by  $\partial\sigma$  and is formulated

$$\partial\sigma = \sum_{i=1}^n (-1)^{i+1} (\phi_{(x_1, \dots, x_{i-1}, 1)} - \phi_{(x_1, \dots, x_{i-1}, 0)})$$

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## Actual Stokes Theorem:

$$\int_C \vec{F} \cdot d\vec{r} = \iint_S \text{Curl} \vec{F} \cdot n d\vec{S}$$

**THANK YOU!**